

FIG. 1

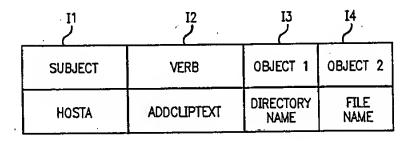


FIG. 2

TITLE: NETWORK SYSTEM AND OBJECT COOPERATION THEREIN INVENTORS: Makoto OKADA, et al.

SERIAL NO.:	Unassigned
DOCKET NO .:	

r					<u> </u>	, <u>-</u>	
91	PROCESSING CONTENT	MOVING THE MOUSE TO THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	PRESSING DOWN THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	OOUBLE CLICK OF THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES.	PRESSING DOWN THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES
4.	OBJECT 2	. *	*	*	*	*	*
E	OBJECT 1 OBJECT 2	*	*	*	*	*	*
27	VERB	MOUSEMOVE	LBUTTONOOWN	LBUTTONUP	LBUTTONDBLCLK	RBUTTONDOWN	RBUTTONUP
F	SUBJECT	*	HOSTA .	HOSTB	ноѕтс	*	*

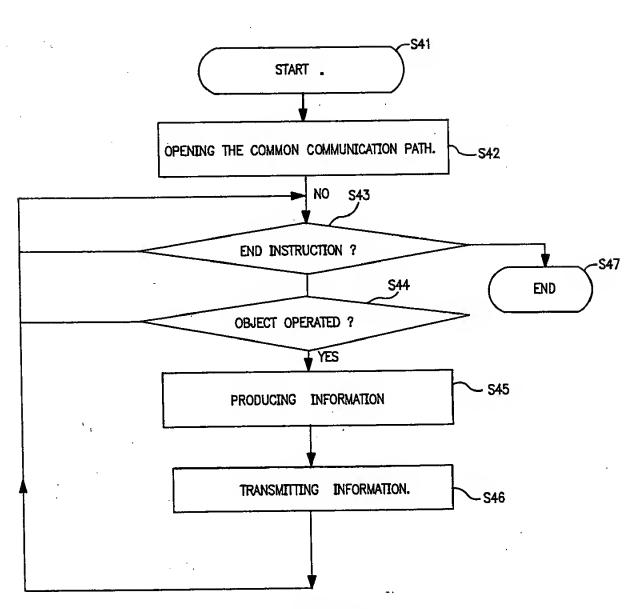


FIG. 4

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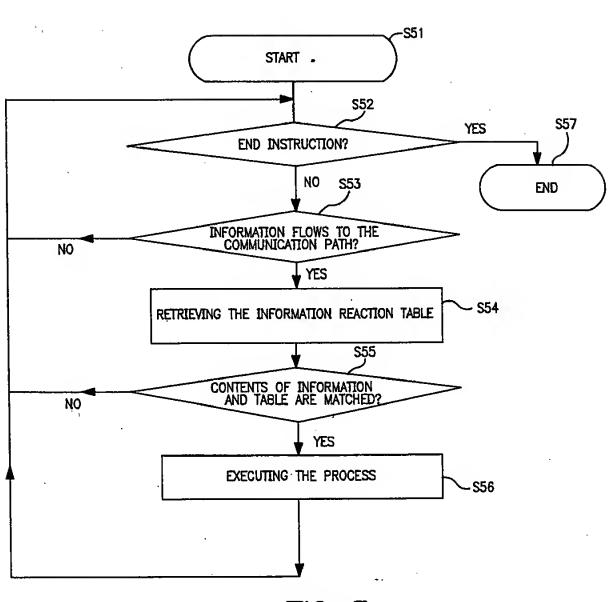


FIG. 5

INVENTORS: Makoto OKADA, et al. SERIAL NO.: Unassigned DOCKET NO.: 21.1886C

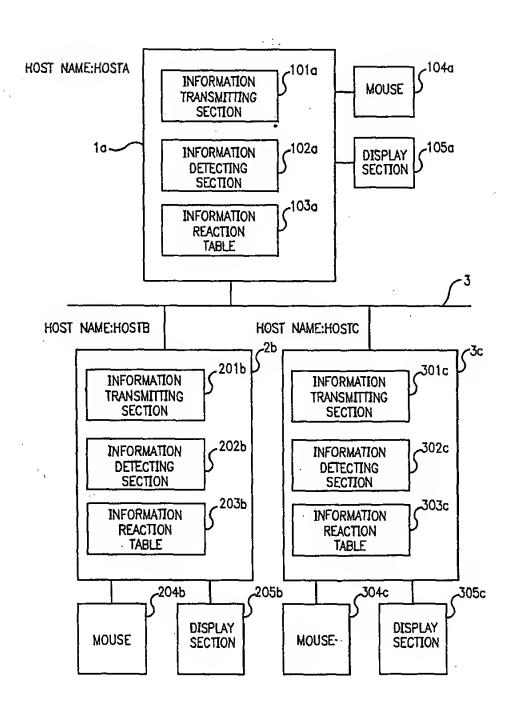
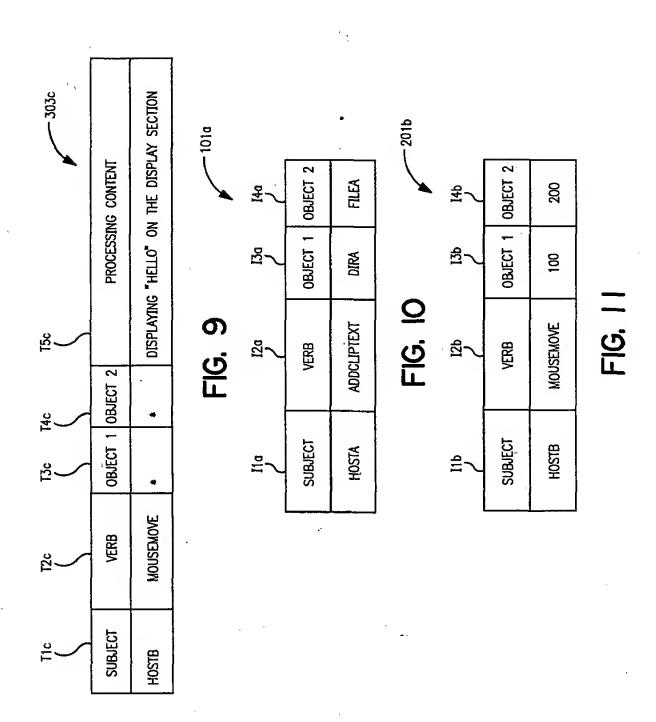


FIG. 6

15a	PROCESSING CONTENT	MOVING THE MOUSE TO THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	PRESSING DOWN THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES.	DOUBLE CLICK OF THE LEFT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	PRESSING DOWN THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES	RELEASING UP THE RIGHT BUTTON AT THE POINT (X,Y) WHERE OBJECT 1 AND OBJECT 2 ARE SET AS THE X,Y COORDINATES
T40	OBJECT 2	*	*		*	*	*
T3a	OBJECT 1 OBJECT	*	*	*	*	*	.
120	VERB	MOUSEMOVE	LBUTTONDOWN	LBUTTONUP	LBUTTONOBLCLK	RBUTTONDOWN'	RBUTTONUP
₽ L	SUBJECT	*	*		*	*	*

203b	PROCESSING CONTENT	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2 AS DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2.4S DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD	COPYING A FILE DEFINING OBJECT 1 AND OBJECT 2 AS DIRECTORY NAME AND FILE NAME TO THE CLIPBOARD
TSb				
14p	OBJECT 1 OBJECT 2	44	*	44
45 -	OBJECT 1	*	*	*
T2b	VERB	ADDCLIPFILE	ADDCLIPTEXT	ADDCLIPMETAFILE:
Tib	SUBJECT	*	*	*



203b	PROCESSING CONTENT	OISPLAYING THE CONTENT OF INQUIRY BY DRIVING QUESTION AND ANSWER SYSTEM	DISPLAYING THE CONTENT OF OECISION REQUEST BY ORIVING DECISION MAKING SYSTEM	NOTIFYING THE IOLE CONDITION BY ORIVING SCHEOULE MANAGEMENT SYSTEM	NOTIFYING THE IDLE CONDITION BY ORIVING SCHEOULE MANAGEMENT SYSTEM
T5b1		OISPLAYING THE CONTEN	DISPLAYING THE CONTENT (NOTIFYING THE JOLE	NOTIFYING THE IDLE
74b1	OBJECT 2		OECISION-MAKING	*	*
13b1	OBJECT 1	*	*	*	
1261	VERB	INQUIRY	DECISION	MEETING	MEETING
Tib.	SUBJECT	*	*	HOSTA	ноѕтс

		.		•
T5c1	PROCESSING CONTENT	DISPLAYING THE CONTENT OF INQUIRY BY DRIVING QUESTION AND ANSWER SYSTEM	NOTIFYING THE IOLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM	NOTIFYING THE IDLE CONDITION BY DRIVING SCHEDULE MANAGEMENT SYSTEM
T4c1	OBJECT 2	*	, **	*
T3c1	OBJECT 1	CLIENT/SERVER SYSTEM	*	*
12c1	VERB	INQUIRY	MEETING	MEETING
Tie.	SUBJECT	*	HOSTA	HOSTB

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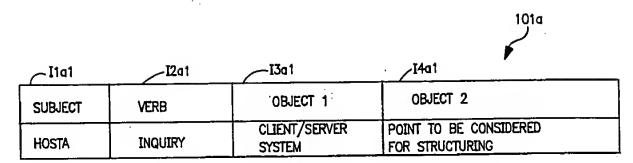


FIG. 14

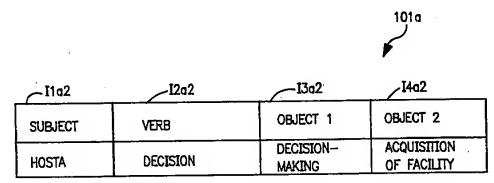


FIG. 15

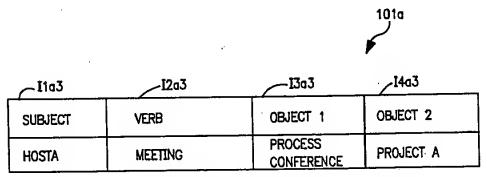


FIG. 16

		:		
RETURNING TO THE FIELD	NONE	MACHING TABLE VALUE	NONE	RETURNING VALUE AFTER EXECUTION OF MACHING FUNCTION
reaction of the other object	REACTION	NON-REACTION	REACTION	REACTION
CONDITION OF FLAG	0	, , ,	0	1
FLAG NAME	INFORM			
T6 -7				

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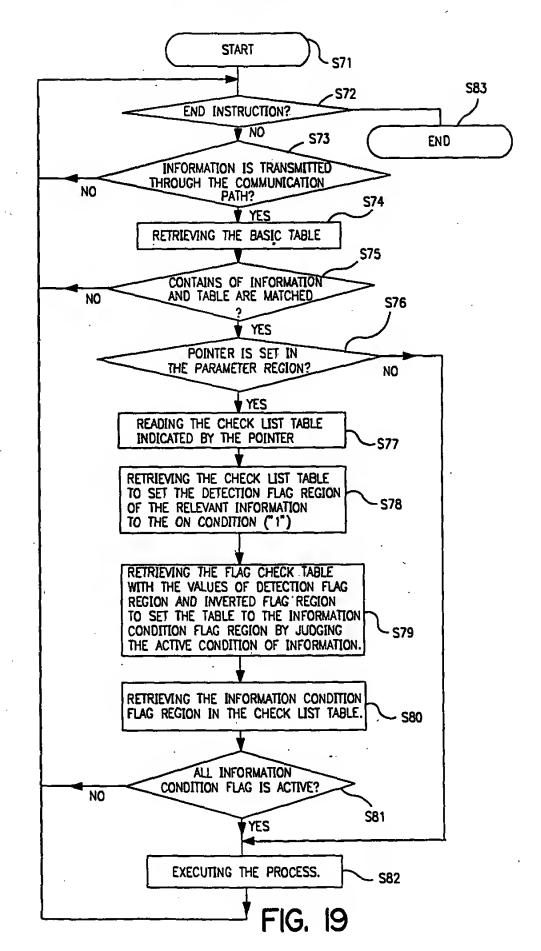
INVENTORS: Makoto OKADA, et al. SERIAL NO.: Unassigned DOCKET NO.: 21.1886C

103a, 203b, 303c JT1 BASIC TABLE 1–111سر $\sqrt{11-2}$ <u>__</u>∭-5 3−∏__ر *— ∭−*4 **∕**∭-6 PROCESSING SUBJECT OBJECT 1 OBJECT 2 **VERB** PARAMETER CONTENT SUBJECT-A VERB-A1 PARAM-A1 ACTION-A1 SUBJECT-B VERB-B1 * ACTION-B1 POINTER-a VERB-C1 SUBJECT-C POINTER- α * ACTION-C1 * POINTER-B SUBJECT-B VERB-B2 ٠ * ACTION-B2 VERB-D1 SUBJECT-C POINTER- β * ACTION-D1 JT2 CHECK LIST TABLE POINTER-α J12-1a J12-2a JT2-50 JT2-7a JT2-3a JT2-4a JT2-60 INFORMATION DETECTED INVERTED SUBJECT CONDITION **VERB** OBJECT 1 OBJECT 2 FLAG FLAG FLAG SUBJECT-B VERB-B1 0 INACTIVE 0 * VERB-C1 SUBJECT-C 0 0 INACTIVE POINTER-B JT2-16 JT2-2b **√ Л2**−7b JT2-3b JT2-4b JT2-5b Л2-6b INFORMATION DETECTED INVERTED SUBJECT **VERB** CONDITION OBJECT 1 OBJECT 2 FLAG FLAG FLAG Subject—B VERB-B2 0 0 INACTIVE VERB-D1 SUBJECT-D 1 * 0 . * **ACTIVE** FLAG CHECK TABLE INVERTED FLAG DETECTED 0 1 FLAG INACTIVE ACTIVE 0 1 **ACTIVE** INACTIVE

FIG. 18

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REACTION CONTROL O ~ JT2-8c 100 INFORMATION CONDITION FLAG ~ JT2-7c INACTIVE INACTIVE ~ JT2-6c INVERTED 0 0 JT2-5c DETECTED FLAG 0 0 . JT2-4c OBJECT # OBJECT 1 ~JT2-3c $\frac{JT2}{POINTER-\alpha}$ CHECK LIST TABLE VERB-B1 VERB-C1 JT2-2c VERB SUBJECT-C SUBJECT SUBJEC-B

FIG. 20

